# 5 V MOSFET Driver Compatible with Single-Phase IMVP8 Controllers

The NCP81253 is a high performance dual MOSFET gate driver in a small 2 mm x 2 mm package, optimized to drive the gates of both high-side and low-side power MOSFETs in a synchronous buck converter. The driver outputs can be placed into a high-impedance state via the tri-state PWM and EN inputs. The NCP81253 comes packaged with an integrated boost diode to minimize external components. A VCC UVLO function guarantees the outputs are low when the supply voltage is low.

#### **Features**

- Space–efficient 2 mm x 2 mm DFN8 Thermally–enhanced Package
- VCC Range of 4.5 V to 5.5 V
- Internal Bootstrap Diode
- 5 V 3-stage PWM Input
- Diode Braking Capability via EN Mid-state
- Adaptive Anti–cross Conduction Circuit Protects against Cross–conduction during FET Turn–on and Turn–off
- Output Disable Control Turns Off both MOSFETs via Enable Pin
- VCC Undervoltage Lockout
- These devices are Pb–free, Halogen–free/BFR–free and are RoHS compliant

### **Typical Applications**

• Power Solutions for Notebook and Desktop Systems



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MARKING DIAGRAM



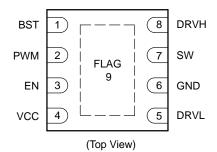
CG = Specific Device Code

M = Date Code

■ = Pb-Free Package

(Note: Microdot may be in either location)

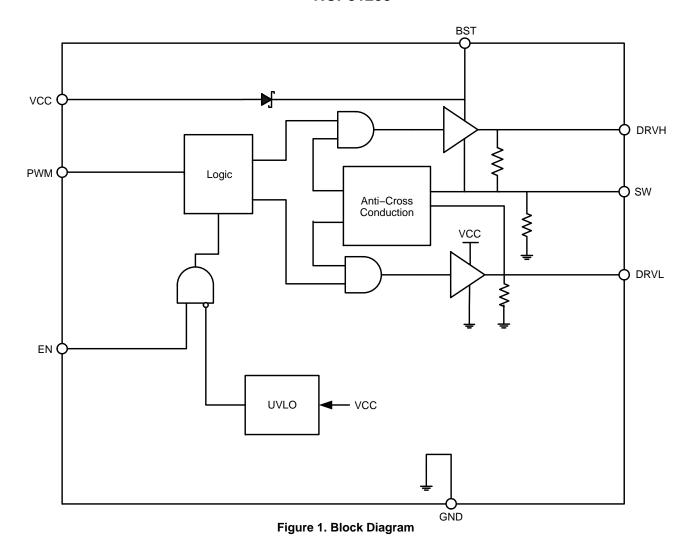
# **PINOUT DIAGRAM**



#### **ORDERING INFORMATION**

Device	Package	Shipping <sup>†</sup>
NCP81253MNTBG	DFN8 (Pb-Free)	3000 / Tape & Reel

†For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specifications Brochure, BRD8011/D.



Pin No.	Pin Name	Description
1	BST	Floating bootstrap supply pin for the high–side gate driver. Connect the external bootstrap capacitor between this pin and SW.
2	PWM	Control input:  PWM = High → DRVH is high, DRVL is low.  PWM = Mid → DRVH and DRVL are low.  PWM = Low → DRVH is low, DRVL is high.
3	EN	3-state input:  EN = High → Driver is enabled; normal PWM operation.  EN = Mid → Driver is enabled; DRVH and DRVL are low (body diode braking).  EN = Low → Driver is disabled.
4	VCC	Power supply input. Connect a bypass capacitor from this pin to ground.
5	DRVL	Low-side gate drive output. Connect to the gate of the low-side MOSFET.
6	GND	Bias and reference ground. All signals are referenced to this node.
7	SW	Switch node. Connect this pin to the source of the high–side MOSFET and drain of the low–side MOSFET.
8	DRVH	High-side gate drive output. Connect to the gate of the high-side MOSFET.
9	FLAG	Thermal flag. There is no electrical connection to the IC. Connect to the ground plane.

**Table 2. ABSOLUTE MAXIMUM RATINGS** 

Rating	Symbol	Min	Max
Main Supply Voltage (Note 1)	V <sub>CC</sub>	-0.3 V	6.5 V
Bootstrap Supply Voltage	BST	-0.3 V wrt/SW	35 V wrt/GND 40 V (≤ 50 ns) wrt/GND 6.5 V wrt/SW
Switch Node Voltage	SW	-5 V -10 V (≤ 200 ns)	35 V 40 V (≤ 50 ns)
High-Side Driver Output	DRVH	-0.3 V wrt/SW -2 V (≤ 200 ns) wrt/SW	BST + 0.3 V wrt/SW
Low-Side Driver Output	DRVL	-0.3 V -5 V (≤ 200 ns)	VCC + 0.3 V
DRVH/DRVL Control Input, Enable Pin	PWM, EN	-0.3 V	6.5 V
Ground	GND	0 V	0 V
Storage Temperature Range	TSTG	–55°C	150°C
Operating Junction Temperature Range	TJ	−40°C	150°C
Moisture Sensitivity Level	MSL		1

Stresses exceeding those listed in the Maximum Ratings table may damage the device. If any of these limits are exceeded, device functionality should not be assumed, damage may occur and reliability may be affected.

#### **Table 3. THERMAL CHARACTERISTICS**

Rating	Symbol	Value	Unit
Thermal Characteristics, DFN8, 2x2 mm (Note 2) Thermal Resistance, Junction–to–Air	$R_{ heta JA}$	119	°C/W

<sup>2.</sup> Values based on copper area of 645 mm2 (or 1 in2) of 1 oz copper thickness and FR4 PCB substrate.

# Table 4. OPERATING RANGES (Note 3)

Rating	Symbol	Min	Max	Unit
Input Voltage	VCC	4.5	5.5	V
Ambient Temperature	T <sub>A</sub>	-40	100	°C

Functional operation above the stresses listed in the Recommended Operating Ranges is not implied. Extended exposure to stresses beyond the Recommended Operating Ranges limits may affect device reliability.

**Table 5. ELECTRICAL CHARACTERISTICS** VCC = 4.5 V to 5.5 V, VBST-SWN = 4.5 V to 5.5 V, BST = 4.5 V to 30 V, SW = 0 V to 21 V; for typical values  $T_A = 25^{\circ}\text{C}$ , for min/max values  $T_A = -40^{\circ}\text{C}$  to  $100^{\circ}\text{C}$ ; unless otherwise noted. (Notes 4, 5)

Parameter	Test Conditions	Symbol	Min	Тур	Max	Unit
SUPPLY VOLTAGE	•					
VCC Operation Voltage		VCC	4.5		5.5	V
UNDERVOLTAGE LOCKOUT	·			•	-	
VCC Start Threshold	VCC rising	$V_{UVLO}$	3.8	4.35	4.5	V
VCC UVLO Hysteresis		$V_{\text{UVLO\_HYS}}$	150	200	250	mV
SUPPLY CURRENT	·					
Shutdown Mode	ICC + IBST, EN = GND	I <sub>shutdown</sub>		1	20	μΑ
Normal Mode	ICC + IBST, EN = 5 V, PWM = 400 kHz No load on driver outputs.	I <sub>normal</sub>		1.6		mA
Standby Current 1	ICC + IBST, EN = 5 V, PWM = 0 V	I <sub>standby</sub>		0.9		mΑ

<sup>4.</sup> Refer to ABSOLUTE MAXIMUM RATINGS and APPLICATION INFORMATION for Safe Operating Area.

<sup>1.</sup> Refer to ELECTRICAL CHARACTERISTIS and APPLICATION INFORMATION for Safe Operating Area.

<sup>3.</sup> Refer to ELECTRICAL CHARACTERISTIS and APPLICATION INFORMATION for Safe Operating Area.

<sup>5.</sup> Performance guaranteed over the indicated operating temperature range by design and/or characterization tested at  $T_J = T_A = 25^{\circ}C$ . Low duty cycle pulse techniques are used during testing to maintain the junction temperature as close to ambient as possible.

**Table 5. ELECTRICAL CHARACTERISTICS** VCC = 4.5 V to 5.5 V, VBST-SWN = 4.5 V to 5.5 V, BST = 4.5 V to 30 V, SW = 0 V to 21 V; for typical values  $T_A = 25^{\circ}\text{C}$ , for min/max values  $T_A = -40^{\circ}\text{C}$  to  $100^{\circ}\text{C}$ ; unless otherwise noted. (Notes 4, 5)

Parameter	Test Conditions	Symbol	Min	Тур	Max	Unit
BOOTSTRAP DIODE		<u>'</u>				
Forward Voltage	VCC = 5 V, Forward bias current = 2 mA		0.1	0.4	0.6	V
PWM INPUT		•				
PWM Input High		PWM <sub>HI</sub>	3.4			V
PWM Mid-State		$PWM_{MID}$	1.3		2.7	V
PWM Input Low		$PWM_{LO}$			0.7	V
HIGH-SIDE DRIVER	•					
Output Impedance, Sourcing Current	VBST – VSW = 5 V			0.9	1.7	Ω
Output Impedance, Sinking Current	VBST – VSW = 5 V			0.7	1.7	Ω
DRVH Rise Time	VCC = 5 V, C <sub>load</sub> = 3 nF, VBST-VSW = 5 V, DRVH-SW = 90% to 10%	tr <sub>DRVH</sub>		16	25	ns
DRVH Fall Time	VCC = 5 V, C <sub>load</sub> = 3 nF , VBST-VSW = 5 V, DRVH-SW = 90% to 10%	tf <sub>DRVH</sub>		11	18	ns
DRVH Turn-Off Propagation Delay	C <sub>load</sub> = 3 nF, PWM = PWM <sub>LO</sub> to DRVH = 90%	tpdl <sub>DRVH</sub>	10	18	30	ns
DRVH Turn-On Propagation Delay	C <sub>load</sub> = 3 nF, DRVL = 1 V to DRVH–SW = 10%	$tpdh_{DRVH} \\$	10	15	40	ns
SW Pull-down Resistance	SW to GND			45		kΩ
DRVH Pull-down Resistance	DRVH to SW			45		kΩ
LOW-SIDE DRIVER						
Output Impedance, Sourcing Current	VCC = 5 V			0.9	1.7	Ω
Output Impedance, Sinking Current	VCC = 5 V			0.4	0.8	Ω
DRVL Rise Time	VCC = 5 V, C <sub>load</sub> = 3 nF, VBST-VSW = 5 V, DRVL = 90% to 10%	tr <sub>DRVL</sub>		11	25	ns
DRVL Fall Time	VCC = 5 V, C <sub>load</sub> = 3 nF , VBST-VSW = 5 V, DRVL = 90% to 10%	tf <sub>DRVL</sub>		8	15	ns
DRVL Turn-Off Propagation Delay	C <sub>load</sub> = 3 nF, PWM = PWM <sub>HI</sub> to DRVL = 90%	tpdl <sub>DRVL</sub>	10	15	30	ns
DRVL Turn-On Propagation Delay	C <sub>load</sub> = 3 nF, DRVH–SW = 1 V to DRVL = 10%	$tpdh_{DRVL}$	5	8	25	ns
DRVL Pull-down Resistance	DRVL to GND, VCC = GND			45		kΩ
EN INPUT						
Enable Voltage High		EN <sub>HI</sub>	3.3			V
Enable Voltage Mid		EN <sub>MID</sub>	1.35		1.8	V
Enable Voltage Low		EN <sub>LO</sub>			0.6	V
Input Bias Current			-1.0		1.0	μΑ
EN High Propagation Delay Time	PWM = 0 V, EN going from 0 V to EN <sub>HI</sub> to DRVL rising to 10%	tpd <sub>EN_HI</sub>		20	40	ns
SWITCH NODE		•				
SW Node Leakage Current					20	μΑ

<sup>4.</sup> Refer to ABSOLUTE MAXIMUM RATINGS and APPLICATION INFORMATION for Safe Operating Area.

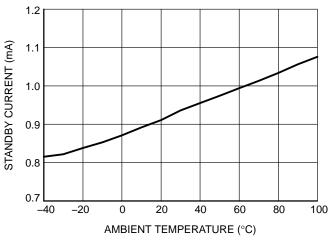
Product parametric performance is indicated in the Electrical Characteristics for the listed test conditions, unless otherwise noted. Product performance may not be indicated by the Electrical Characteristics if operated under different conditions.

Performance guaranteed over the indicated operating temperature range by design and/or characterization tested at T<sub>J</sub> = T<sub>A</sub> = 25°C. Low duty cycle pulse techniques are used during testing to maintain the junction temperature as close to ambient as possible.

### **TYPICAL CHARACTERISTICS**

40 35

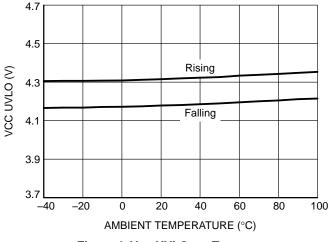
30 25 20



SUPPLY CURRENT (mA) 15 10 100 200 300 700 800 900 1000 400 500 600 SWITCHING FREQUENCY (kHz)

Figure 2. Standby Current vs. Temperature  $(V_{CC} = 5 \text{ V}, EN = 5 \text{ V}, PWM = 0 \text{ V})$ 

Figure 3. Supply Current vs. Switching Frequency (V<sub>CC</sub> = 5 V, C<sub>load</sub> = 3 nF)



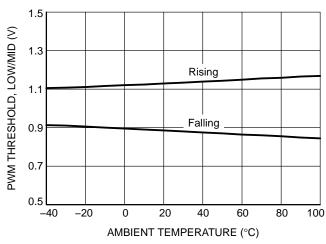
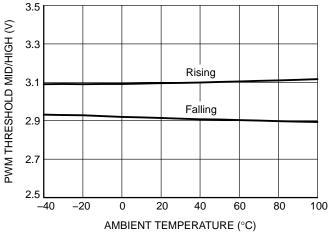


Figure 4.  $V_{CC}$  UVLO vs. Temperature (EN = 5 V)

Figure 5. PWM Low/Mid Thresholds vs. Temperature  $(V_{CC} = 5 V)$ 



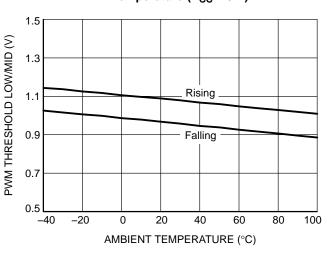
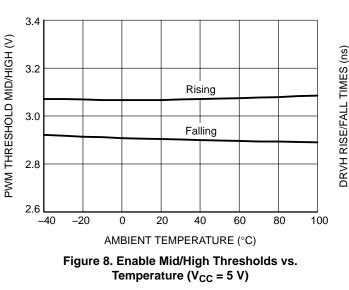


Figure 6. PWM Mid/High Thresholds vs. Temperature ( $V_{CC} = 5 V$ )

Figure 7. Enable Low/Mid Thresholds vs. Temperature ( $V_{CC} = 5 V$ )

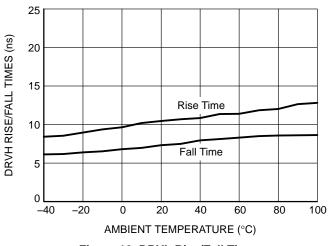
#### **TYPICAL CHARACTERISTICS**

25



20 Rise Time
15 Fall Time
10 AMBIENT TEMPERATURE (°C)

Figure 9. DRVH Rise/Fall Times vs. Temperature ( $V_{BST} - V_{SW} = 5 \text{ V}, C_{load} = 3 \text{ nF}$ )



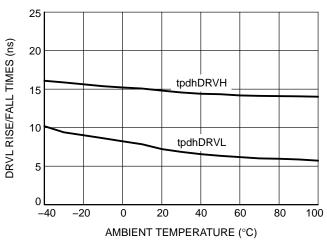
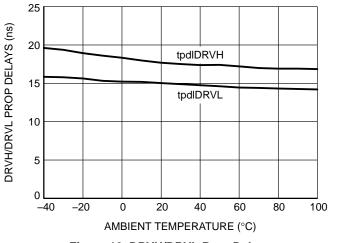


Figure 10. DRVL Rise/Fall Times vs. Temperature (V<sub>CC</sub> = 5 V, C<sub>load</sub> = 3 nF)

Figure 11. Dead Times vs. Temperature  $(V_{CC} = 5 \text{ V}, C_{load} = 3 \text{ nF})$ 



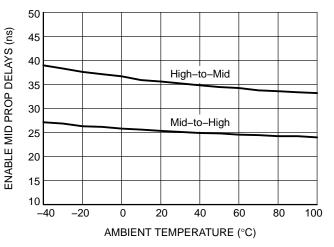


Figure 12. DRVH/DRVL Prop Delays vs. Temperature ( $V_{CC} = 5 \text{ V}, C_{load} = 3 \text{ nF}$ )

Figure 13. Enable Mid Prop Delays vs. Temperature (V<sub>CC</sub> = 5 V, C<sub>load</sub> = 3 nF)

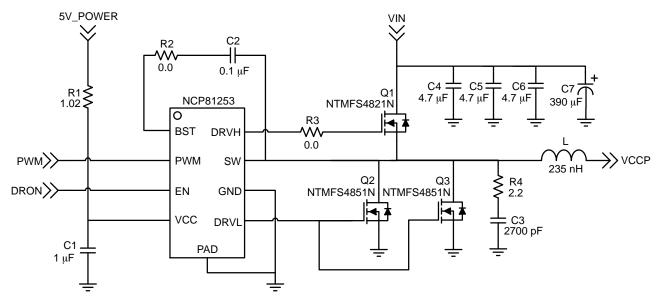


Figure 14. Application Circuit

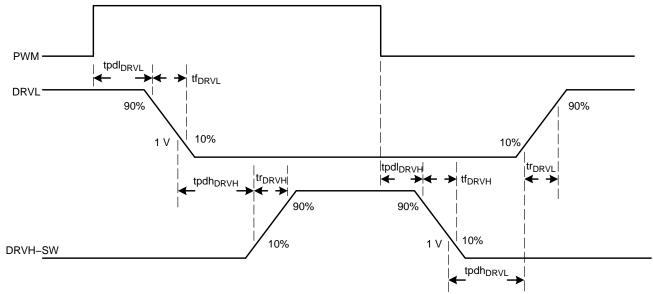


Figure 15. Gate Timing Diagram

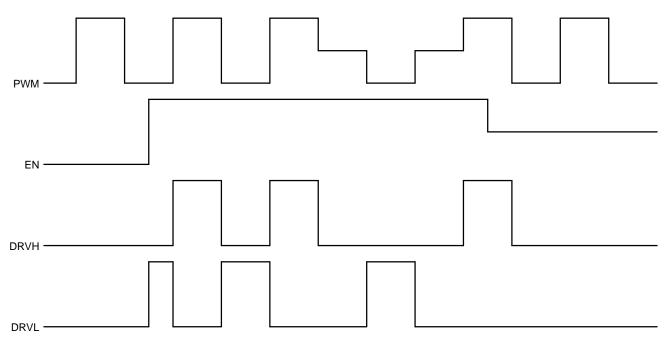


Figure 16. PWM/EN Logic Diagram

#### APPLICATIONS INFORMATION

The NCP81253 gate driver is a single–phase MOSFET driver designed for driving N–channel MOSFETs in a synchronous buck converter topology. The NCP81253 is designed to work with single–phase IMVP8 controllers such as the NCP81206.

#### Low-Side Driver

The low–side driver is designed to drive a ground–referenced low–R<sub>DS(on)</sub> N–channel MOSFET. The voltage supply for the low–side driver is internally connected to the VCC and GND pins.

# **High-Side Driver**

The high–side driver is designed to drive a floating low–R<sub>DS(on)</sub> N–channel MOSFET. The gate voltage for the high–side driver is developed by a bootstrap circuit referenced to the SW pin.

The bootstrap circuit is comprised of the integrated diode and an external bootstrap capacitor. When the NCP81253 is starting up, the SW pin is held at ground, allowing the bootstrap capacitor to charge up to VCC through the bootstrap diode. When the PWM input is driven high, the high–side driver will turn on the high–side MOSFET using the stored charge of the bootstrap capacitor. As the high–side MOSFET turns on, the SW pin rises. When the high–side MOSFET is fully turned on, SW will settle to VIN and BST will settle to VIN + VCC (excluding parasitic ringing).

#### **Bootstrap Circuit**

The bootstrap circuit relies on an external charge storage capacitor (C<sub>BST</sub>) and an integrated diode to provide current to the high-side driver. A multi-layer ceramic capacitor (MLCC) with a value greater than 100 nF should be used for C<sub>BST</sub>.

### **Power Supply Decoupling**

The NCP81253 can source and sink relatively large currents to the gate pins of the MOSFETs. In order to maintain a constant and stable supply voltage, a low–ESR capacitor should be placed near the VCC and GND pins. A MLCC between 1  $\mu$ F and 4.7  $\mu$ F is typically used.

#### **Undervoltage Lockout**

DRVH and DRVL are low until VCC reaches the VCC UVLO threshold, typically 4.35 V. Once VCC reaches this threshold, the PWM signal will control DRVH and DRVL. There is a 200 mV hysteresis on VCC UVLO. There are pull–down resistors on DRVH, DRVL and SW to prevent the gates of the MOSFETs from accumulating enough charge to turn on when the driver is powered off.

# Three-State EN Input

Placing EN into a logic—high and logic—low will turn the driver on and off, respectively, as long as VCC is greater than the UVLO threshold. The EN threshold limits are specified

in the electrical characteristics table in this datasheet. Setting the voltage on EN to a mid-state level will pull both DRVH and DRVL low. Refer to Table 6 for the EN/PWM logic table.

Setting EN to the mid-state level can be used for body diode braking to quickly reduce the inductor current. By turning the LS FET off and having the current conduct through the LS FET body diode, the voltage at the switch node will be at a greater negative potential compared to having the LS FET on. This greater negative potential on switch node allows there to be a greater voltage across the output inductor, since the opposite terminal of the inductor is connected to the converter output voltage. The larger voltage across the inductor causes there to be a greater inductor current slew rate, allowing the current to decrease at a faster rate.

#### Three-State PWM Input

Switching PWM between logic-high and logic-low states will allow the driver to operate in continuous conduction mode as long as VCC is greater than the UVLO threshold and EN is high. The threshold limits are specified in the electrical characteristics table in this datasheet. Refer to Figure 15 for the gate timing diagrams and Table 6 for the EN/PWM logic table.

When PWM is set above PWM $_{HI}$ , DRVL will first turn off after a propagation delay of tpdl $_{DRVL}$ . To ensure non–overlap between DRVL and DRVH, there is a delay of tpdh $_{DRVH}$  from the time DRVL falls to 1 V, before DRVH is allowed to turn on.

When PWM falls below PWM $_{LO}$ , DRVH will first turn off after a propagation delay of tpdl $_{DRVH}$ . To ensure non–overlap between DRVH and DRVL, there is a delay of tpdh $_{DRVL}$  from the time DRVH – SW falls to 1 V, before DRVL is allowed to turn on.

When PWM enters the mid-state voltage range (and thereby exiting the logic high or logic low states), both DRVH and DRVL are pulled low for the non-overlap delay (tpdh). If PWM is still in the mid-state at the conclusion of the non-overlap delay, both DRVH and DRVL will remain in the off states.

To minimize power consumption when the NCP81253 is in a disabled state, the internal voltage rails that determine the low/mid/high PWM logic states are shut down when EN is low. When EN is brought high (while VCC is above the UVLO threshold), the PWM internal voltage rails are

brought up, but require some time to rise to their proper levels. To prevent a PWM signal from being interpreted incorrectly during this time, there is a delay from EN rising to the driver responding to PWM signals, which is set at a typical value of  $50 \, \mu s$ .

Table 6. EN/PWM LOGIC TABLE

EN	PWM	DRVH	DRVL
LOW	Х	LOW	LOW
HIGH	LOW	LOW	HIGH
HIGH	MID	LOW	LOW
HIGH	HIGH	HIGH	LOW
MID	LOW	LOW	LOW
MID	MID	LOW	LOW
MID	HIGH	LOW	LOW

#### **Thermal Considerations**

As power in the NCP81253 increases, it might become necessary to provide some thermal relief. The maximum power dissipation supported by the device is dependent upon board design and layout. Mounting pad configuration on the PCB, the board material, and the ambient temperature affect the rate of junction temperature rise for the part. When the NCP81253 has good thermal conductivity through the PCB, the junction temperature will be relatively low with high power applications. The maximum dissipation the NCP81253 can handle is given by:

$$P_{D(MAX)} = \frac{\left[T_{J(MAX)} - T_{A}\right]}{R_{A,IA}}$$
 (eq. 1)

Since  $T_J$  is not recommended to exceed 150°C, the NCP81253, soldered on to a 645 mm<sup>2</sup> copper area, using 1 oz. copper and FR4, can dissipate up to 1.05 W when the ambient temperature ( $T_A$ ) is 25°C. The power dissipated by the NCP81253 can be calculated from the following equation:

$$\begin{aligned} \text{P}_{\text{D}} &\approx \text{VCC} \cdot \left[ (\text{n}_{\text{HS}} \cdot \text{Qg}_{\text{HS}} + \text{n}_{\text{LS}} \cdot \text{Qg}_{\text{LS}}) \cdot f + \text{I}_{\text{standby}} \right] \end{aligned}$$

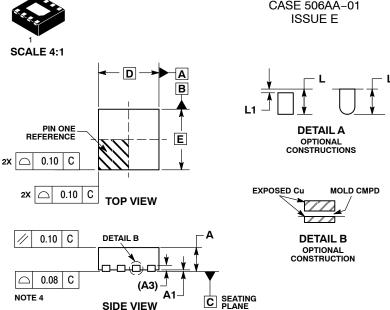
Where  $n_{HS}$  and  $n_{LS}$  are the number of high-side and low-side FETs, respectively,  $Qg_{HS}$  and  $Qg_{LS}$  are the gate charges of the high-side and low-side FETs, respectively and f is the switching frequency of the converter.

DETAIL A

е

- D2 →

**BOTTOM VIEW** 



0.10 C

Ф

AB

0.05 C NOTE 3



**DATE 22 JAN 2010** 

#### NOTES

- DIMENSIONING AND TOLERANCING PER
- ASME Y14.5M, 1994 . CONTROLLING DIMENSION: MILLIMETERS.
- DIMENSION b APPLIES TO PLATED TERMINAL AND IS MEASURED BETWEEN
- 0.15 AND 0.20 MM FROM TERMINAL TIP. COPLANARITY APPLIES TO THE EXPOSED PAD AS WELL AS THE TERMINALS.

	MILLIMETERS			
	MILLIN	IE I EKS		
DIM	MIN	MAX		
Α	0.80	1.00		
A1	0.00	0.05		
A3	0.20	REF		
b	0.20	0.30		
D	2.00	BSC		
D2	1.10	1.30		
E	2.00	BSC		
E2	0.70	0.90		
е	0.50 BSC			
K	0.30 REF			
L	0.25 0.35			
L1	0.10			

# **GENERIC MARKING DIAGRAM\***



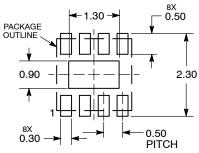
XX = Specific Device Code

= Date Code = Pb-Free Device

\*This information is generic. Please refer to device data sheet for actual part marking.

Pb-Free indicator, "G" or microdot " ■", may or may not be present.

# **RECOMMENDED SOLDERING FOOTPRINT\***



**DIMENSIONS: MILLIMETERS** 

\*For additional information on our Pb-Free strategy and soldering details, please download the ON Semiconductor Soldering and Mounting Techniques Reference Manual, SOLDERRM/D.

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